



Regional Reference Frames for North America

Current Status & Future Plans of Sub-commission 1.3c

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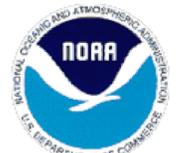
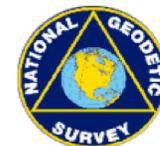
U.S. National Geodetic Survey

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Natural Resources
Canada

Ressources naturelles
Canada

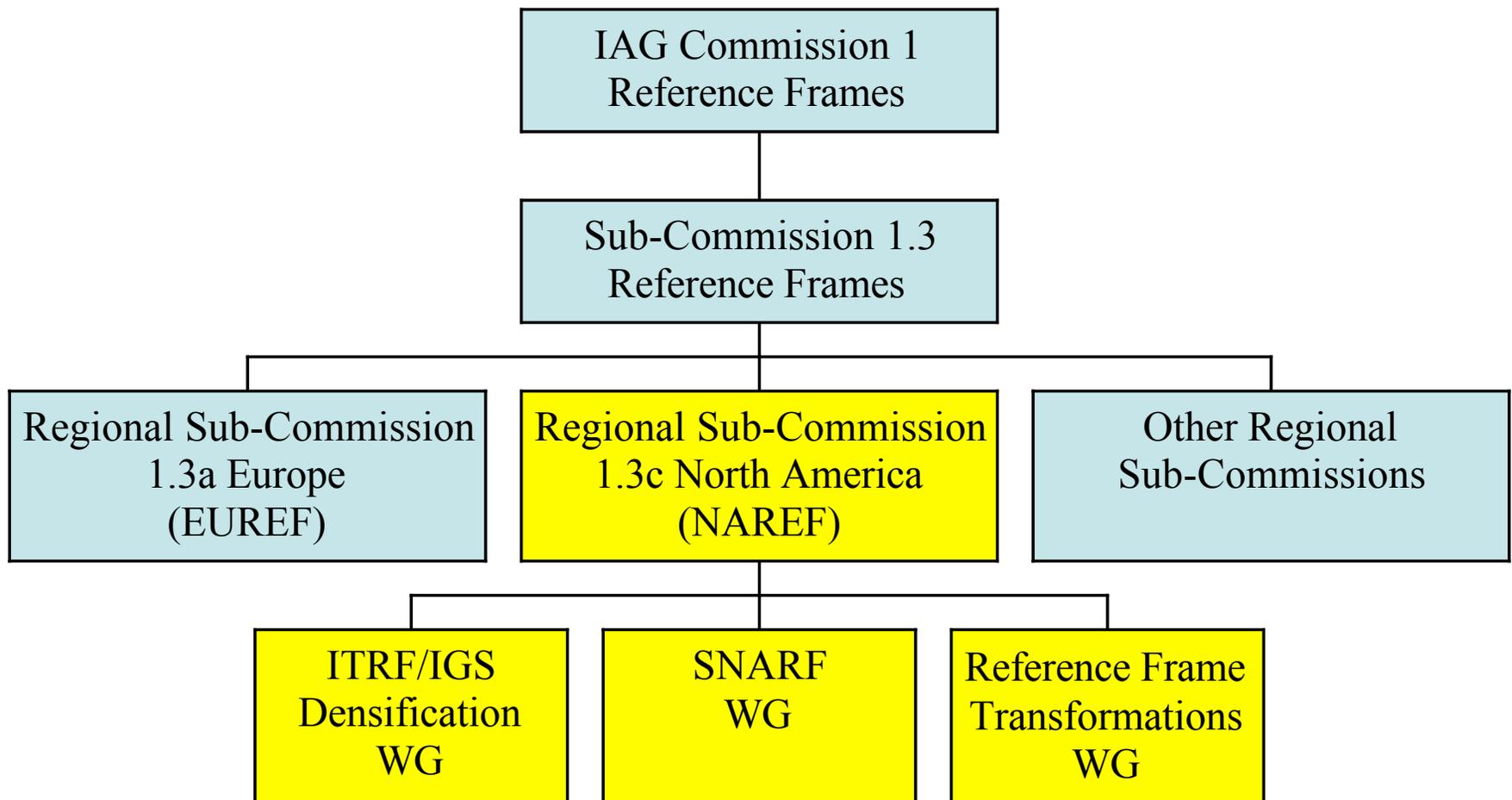


Outline

- Regional Sub-commission 1.3c
- ITRF/IGS Densification Working Group
- Stable N.A. Reference Frame Working Group
- Transformations Working Group

Sub-Commission 1.3c Objective

To provide international focus and cooperation for issues involving the geodetic reference frames of North America



ITRF/IGS Densification Working Group

Objective

- Densify ITRF/IGS global reference frame in N.A.
 - Combining 6 regional solutions
 - Includes most continuous GPS sites in N.A. (~800 sta)
- Following IGS processing standards
 - Fixed orbits/EOP's used in most regional solutions

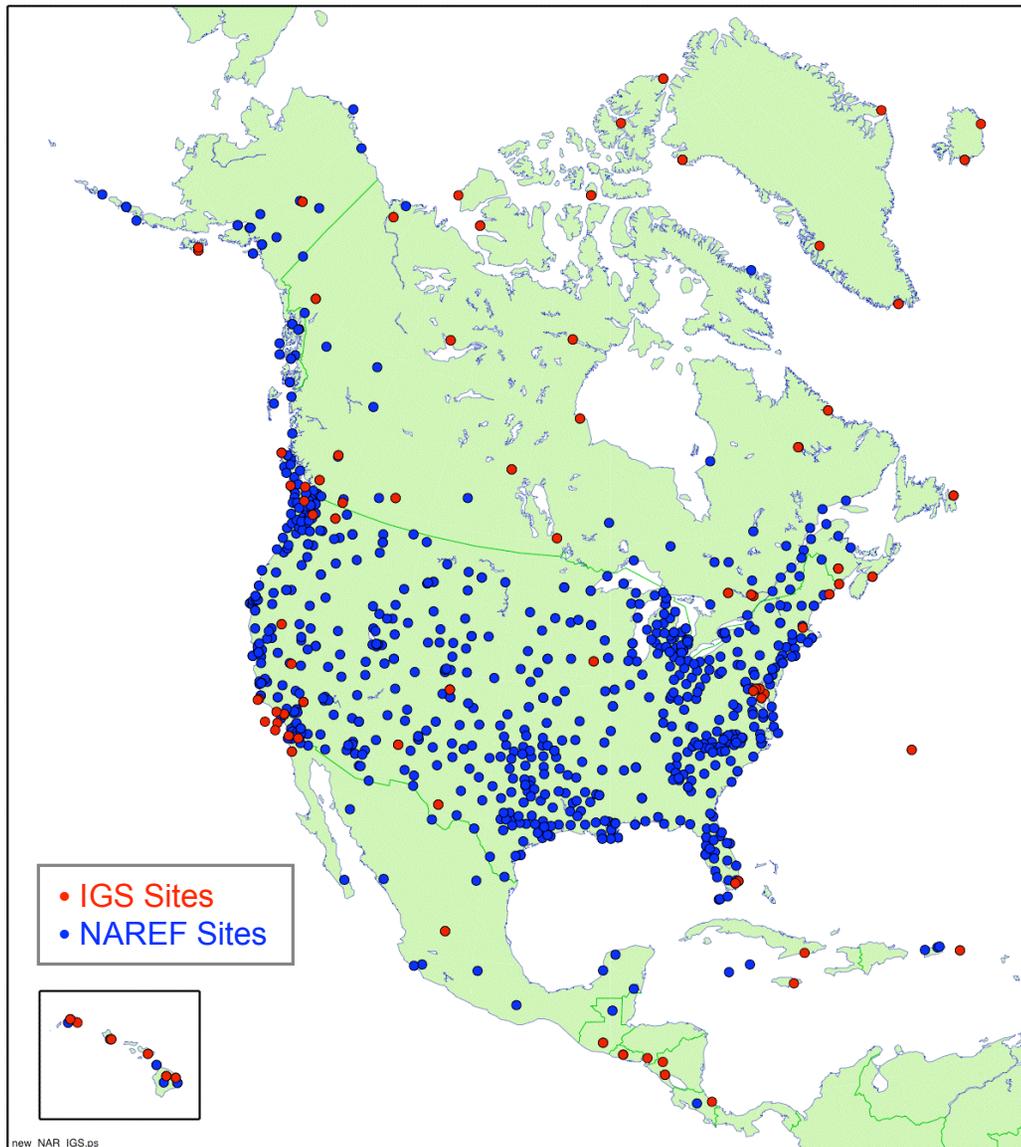
Products

- Weekly coordinate solutions
- Annual velocity solutions

Contributing Regional Solutions

<u>Contributor</u>	<u>Since</u>	<u>Software</u>	<u>Region (# stations wk 1367)</u>
GSD/NRCan	2001	Bernese	Northern N.A. (104)
GSD/NRCan	2001	GIPSY	Canada (42)
PGC/NRCan	2001	Bernese	Western Canada (54)
SIO	2001	GAMIT	Western N.A. (149)
NGS	2002	PAGES	USA and Central Am.(706)
MIT	2004	Combination (GIPSY,GAMIT)	Western & Central N.A. (172)

NAREF Densification Network



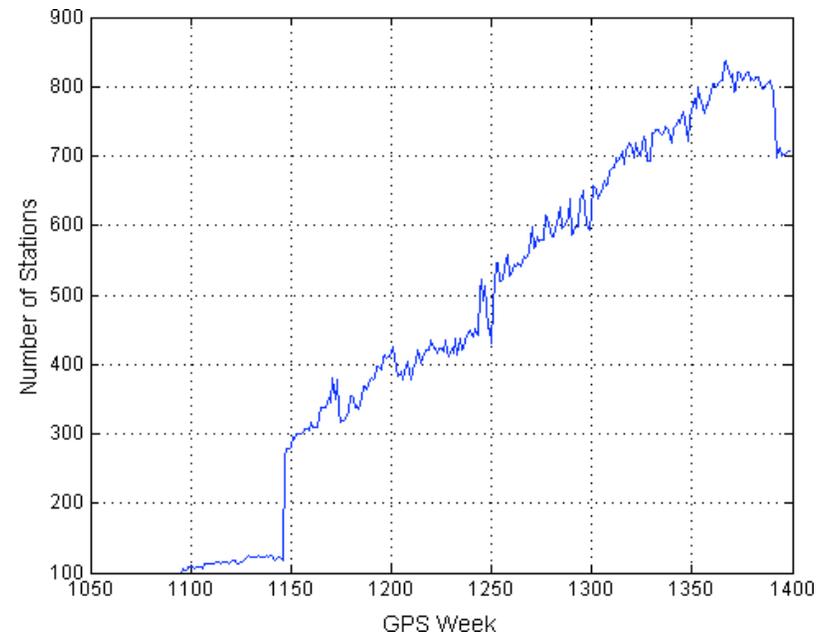
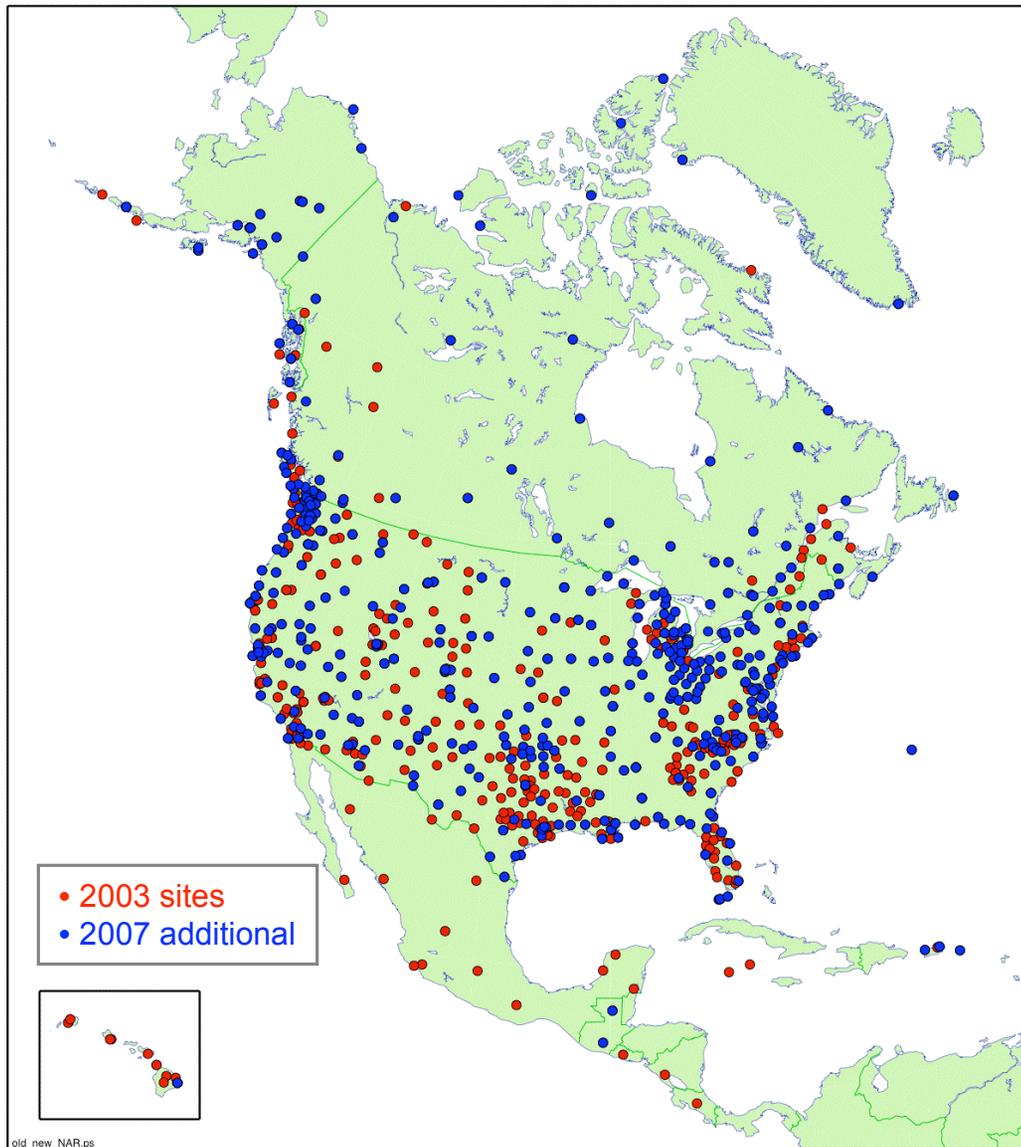
GPS Week 1367

ITRF/IGS Frame Sites	55
NAREF Densification	783
Total	838

Number of Stations in

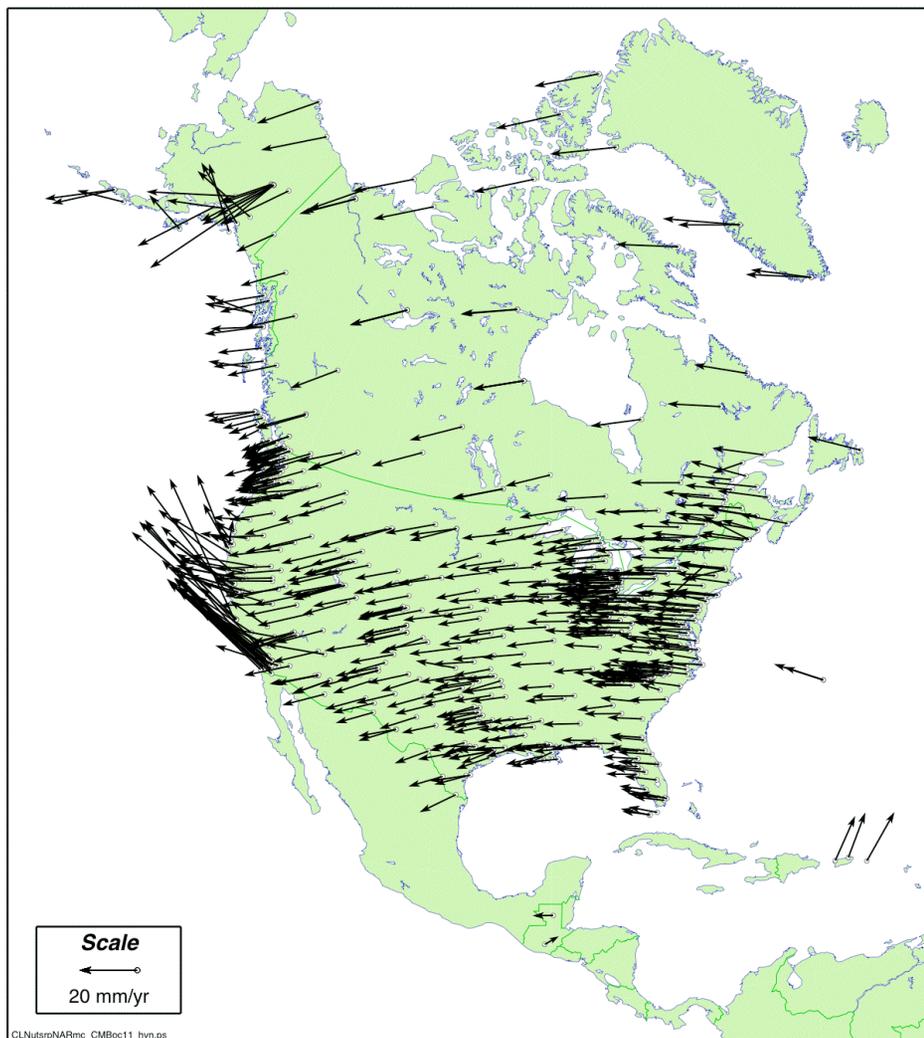
1 solution	607
2 solutions	105
3 solutions	101
4 solutions	20
5 solutions	3
6 solutions	2

Network Growth

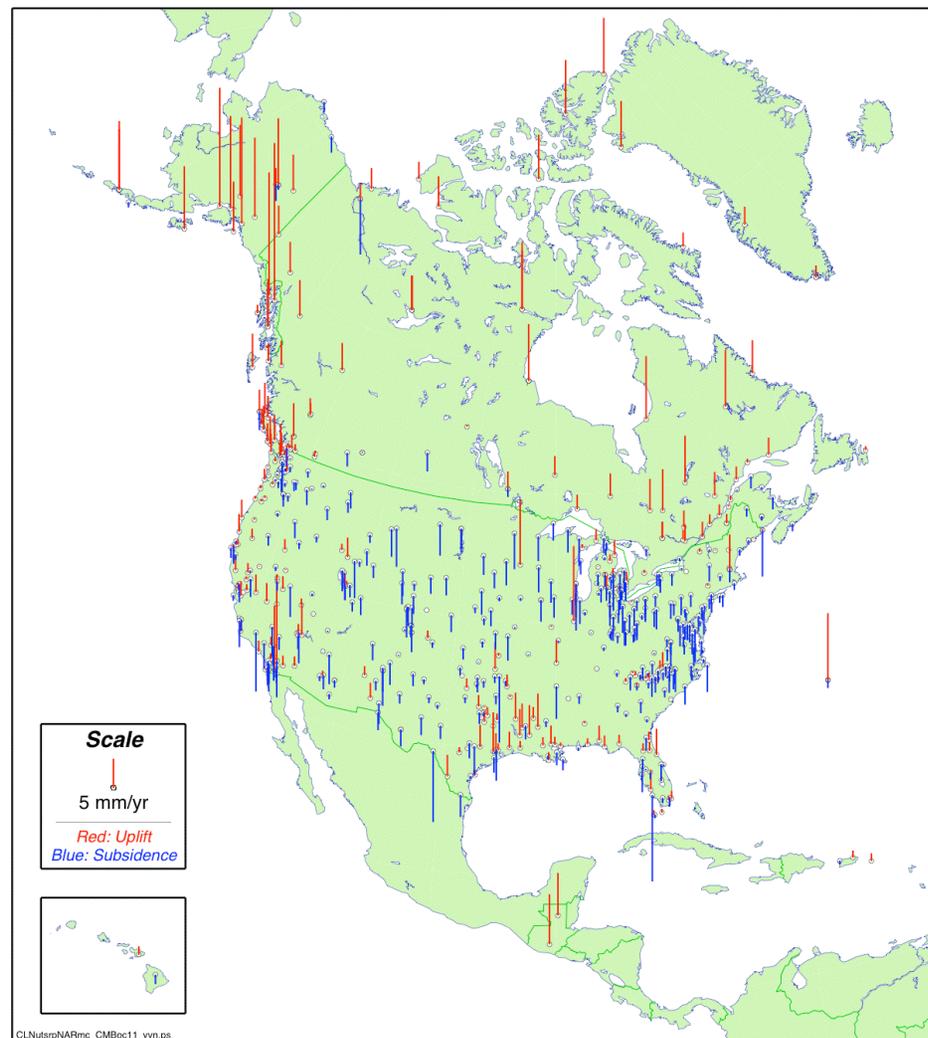


NAREF Velocity Field

Horizontal



Vertical



Future Plans

Solutions since GPS week 1400

- Based on absolute antenna phase centers (APCV's)
- SIO to expand solution to cover entire N.A.
 - More stations in 2 or more solutions
- **Combinations currently on hold**
 - NGS & PGC still updating to new IGS procedures
 - SIO waiting for selection of sub-set of CORS sites (can't include all)

Reprocessing with updated IGS orbits (w/ APCV's)

- Waiting for IGS reprocessing to begin
- Contributors expected to reprocess all data
- Some will reprocess data back to 1994

Stable North American Reference Frame (SNARF) Working Group

Objective

- Define a reference frame that represents the stable interior of North America (plate-fixed)
- To provide a standard to facilitate
 - Inter-comparison of velocity solutions
 - Geophysical interpretation (easier to interpret intra-plate motions)
- Primarily for EarthScope/PBO studies in U.S.
- Joint Working Group with UNAVCO, Inc.

Possible successor to NAD 83

- NAD 83 offset from geocenter (ITRF/WGS) ~2 m

SNARF Approach

Determine a velocity model that brings stable North America to rest

Velocity model includes

- Rotation rates (plate motion)
- Translation rates (bias in GPS velocities?)
- GIA Motion (largest intra-plate motions)

$$\vec{V}_{\text{GPS}}(\lambda, \phi) = \vec{V}_{\text{GIA}}(\lambda, \phi) + \delta\vec{\Omega} \times \hat{r}(\lambda, \phi) + \delta\vec{T}$$

Based on ITRF/IGS reference frame

A Priori GIA Model

Average of a suite of GIA models

- No consensus on Earth models so using a suite of Earth models
- Initially using ICE-1 as basis of GIA (Peltier & Andrews, 1976)
 - Easier to work with for proof-of-concept
 - Will be attempt to use ICE-3G in future version but ...
 - Some Earth model parameters hard-wired into ICE-3G
- Using a range of Earth model parameters for ICE-1G
 - Lithospheric thickness
 - Upper & lower mantle viscosities
 - Based on commonly used values

Full covariance matrix used

- Constructed empirically from variation of suite of models

GPS Velocities

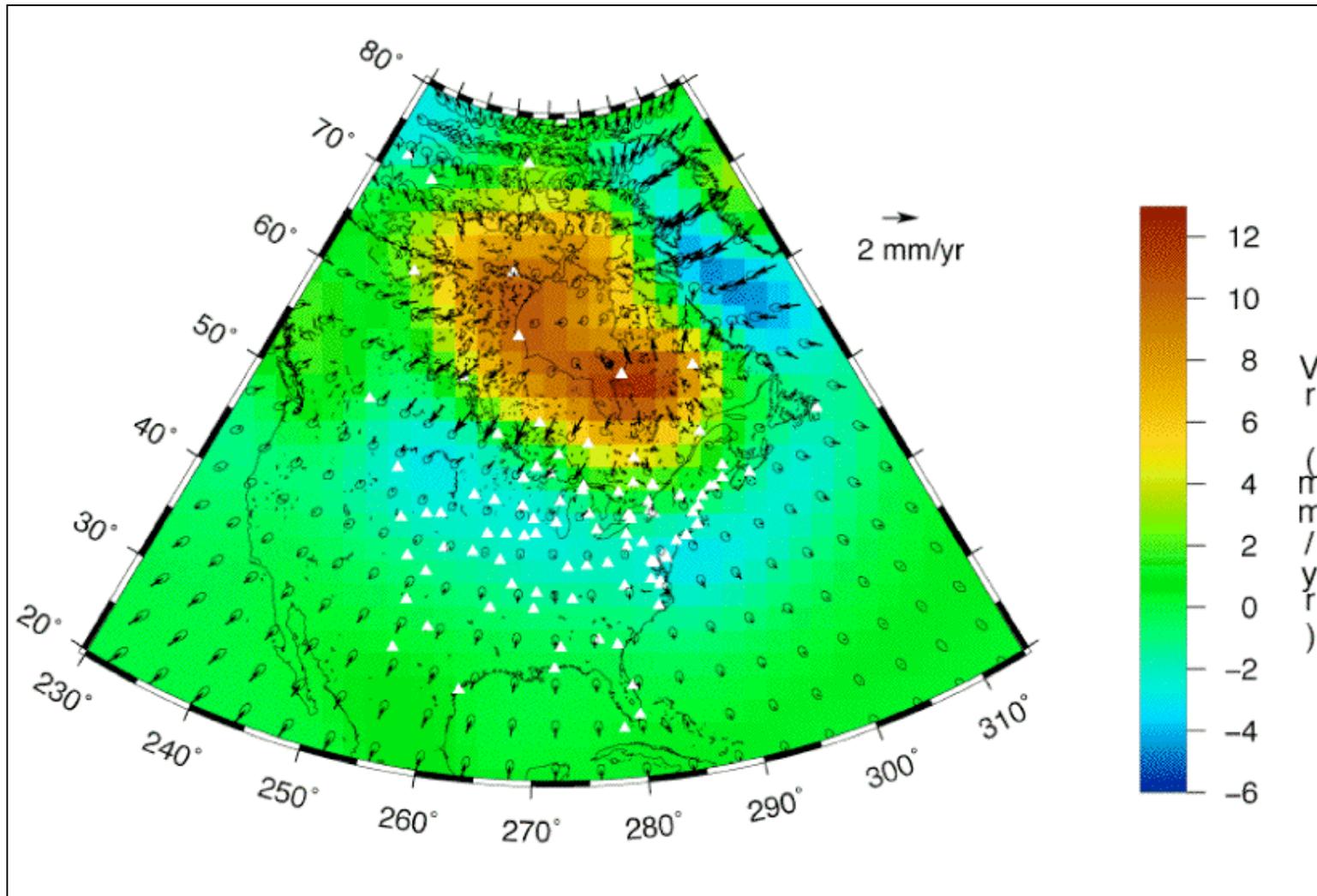
Combination of 3 solutions in IGb00 frame

- NAREF velocity solution for N.A.
 - Combination of 6 regional solutions
- Purdue solution for eastern N.A. (Calais et al, JGR 2006)
- Canadian Base Network (CBN) densification solution for Canada
 - ~180 stations with 28 repeated GPS campaigns (2004-2002)

Combined solution

- Origin and orientation loosely constrained
- SNARF frame defined by best “datum” points (118)
 - Stable monumentation
 - > 3 year time span

SNARF v1.0 GIA Model



SNARF Products

Positions & velocities of all GPS sites

- If velocity of a site matches GIA velocity, it is on stable N.A.
- Differences represent non-GIA motion
- Official PBO solutions provided in SNARF v1.0

GIA model velocities

- Give at GPS sites & on 2°x2° grid for interpolation

SNARF plate motion estimate (Euler rotations)

	ω_x	ω_y	ω_z	
SNARF (wrt IGB00)	0.06588	-0.66708	-0.08676	(mas/y)
ITRF2000	0.08316	-0.69084	-0.06120	
NNR NUVEL-1A	0.0532	-0.7423	-0.0316	

Future Plans

SNARF v2

- Expand list of “datum” sites
 - 60 more, if monumentation can be verified)
- Incorporate new/updated regional solutions
 - Latest NAREF solution
 - Alaska & N.W Canada GIPSY solution (Freymueller)
 - North American GIPSY solution (Blewitt et al.)
 - Updated CBN solution with 2005/6 campaigns

Transition from research mode to operational mode

- National geodetic agencies in US & Can expected to assume responsibility for maintaining SNARF
- *SNARF may possibly supercede NAD 83 in future*

Transformations Working Group

Objective

- To determine consistent relationships between international, regional and national reference frames, and to update these relationships as needed

NAD83-ITRF relationship

- NAD83 still the primary horizontal/3D reference frame for N.A.
- Now defined by 14-parameter transformations from/to ITRF
 - Originally a 7-parameter transformation w.r.t. ITRF97
 - Updated to other ITRF's using official IERS 14-parameter transformations between ITRF's
 - NNR NUVEL-1A used for N.A. plate motion (biased ~ 2 mm/y)
- Transformation recently updated for ITRF2005

For More Information

www.naref.org

Thank you Giovanni !