

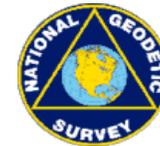
# Evolving Beyond NAD 83

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NATIONAL OCEANIC AND ATMOSPHERIC ADMINISTRATION  
National Ocean Service  
National Geodetic Survey



*Positioning America for the Future*



Natural Resources  
Canada

Ressources naturelles  
Canada

# North American Datum of 1983 (NAD 83)

- \* NAD 83 is the legal reference system in the United States, Canada, Greenland, and in several Caribbean and Central American countries. (Mexico uses the ITRS.)
- \* National Geodetic Survey is responsible agency in the U.S.
- \* Natural Resources Canada is responsible agency in Canada.

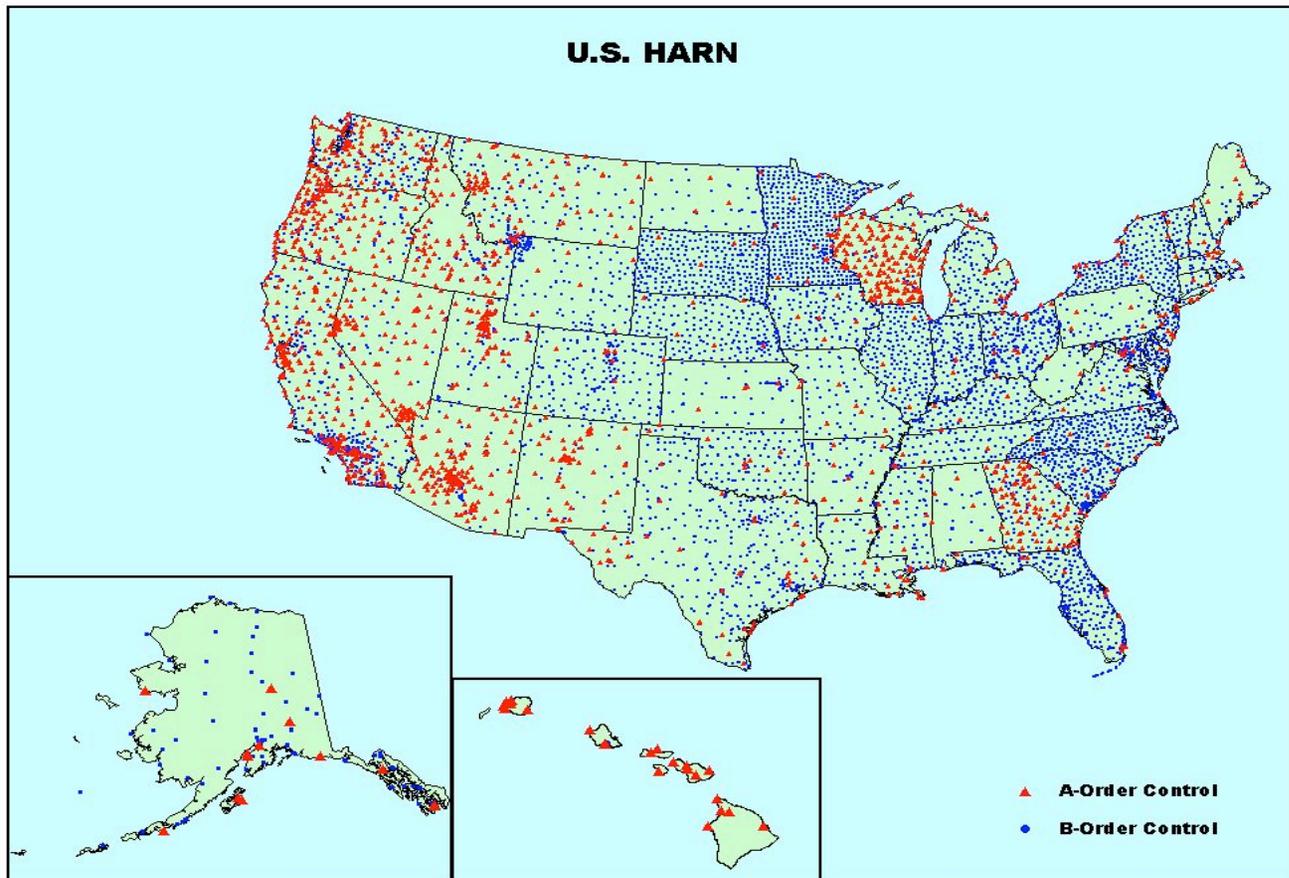
# NAD 83

- Originally, NAD 83 was mostly a horizontal reference system as defined by the latitudes and longitudes of reference stations positioned by triangulation and/or trilateration. (The U.S. contains over 250,000 horizontal reference stations.)
- NAD 83 has evolved to a 3-D reference system, thanks to GPS. (The U.S. contains over 60,000 reference stations positioned by GPS.)

# IMPROVING POSITIONAL ACCURACY

REFERENCE FRAME	TIME SPAN	NETWORK ACCURACY	LOCAL ACCURACY
NAD 27	1927-1986	10 Meters	First-Order (1 part in 0.1 million)
NAD 83(1986) NAD 83(Original)	1986-1990	1 Meter	First-Order (1 part in 0.1 million)
NAD 83(HARN)	1987-1997	0.1 Meter	B-Order (1 part in 1 million) A-Order (1 part in 10 million)
NAD 83(CORS) NAD 83(CSRS)	1994 -	 $< 0.01$ Meter - Horizontal $< 0.02$ Meter - Ellipsoid Height	

# HIGH ACCURACY REFERENCE NETWORKS (HARN)

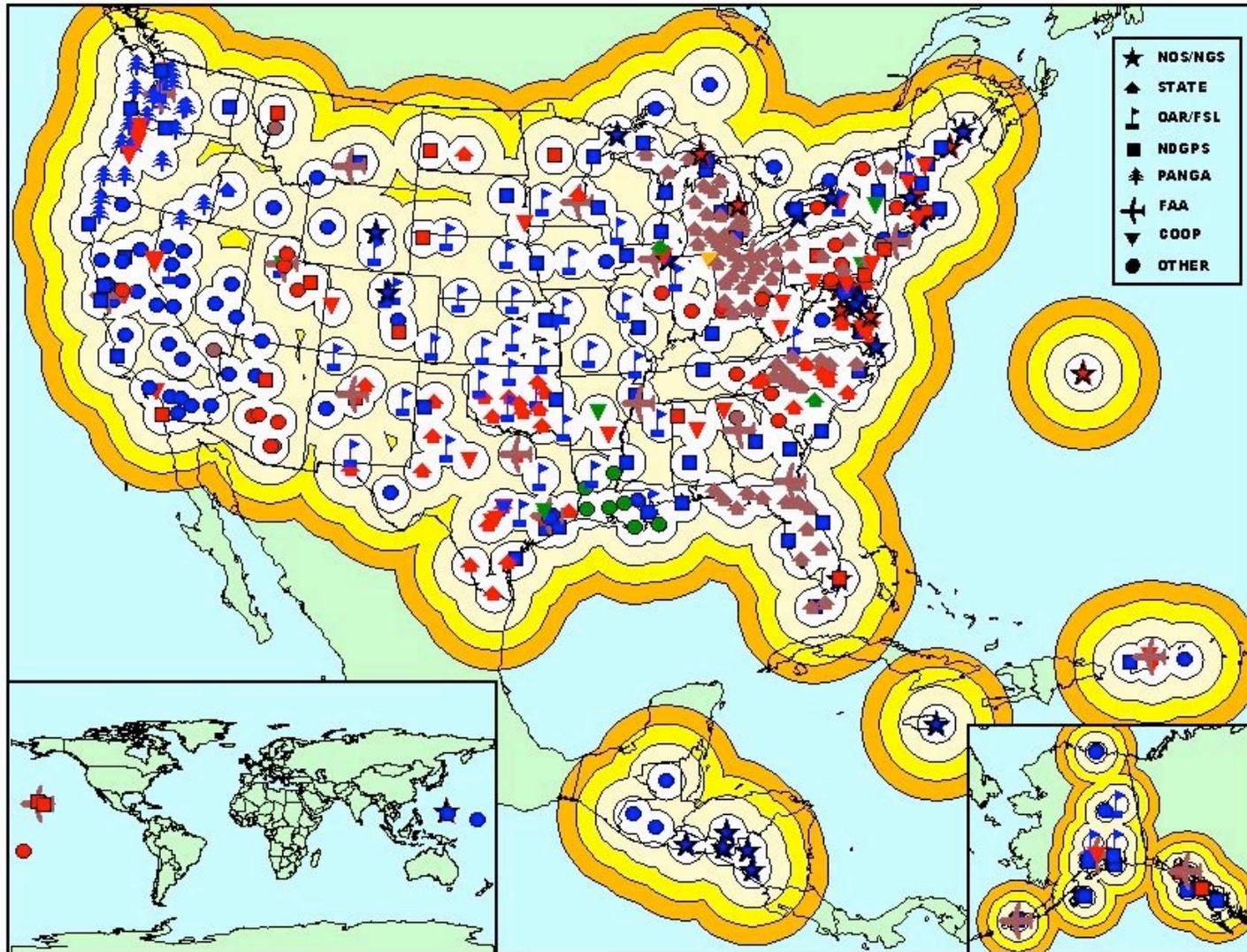


# Canadian Base Network (CBN)



# Continuously Operating Reference Stations

CORS Coverage (100, 200, 300, and 400 km radius) August 2003



Symbol color denotes sampling rates: (1 second) (5 seconds) (15 seconds) (30 seconds)

Craig 7/31/2003

# Canadian Active Control Network (CACNS)

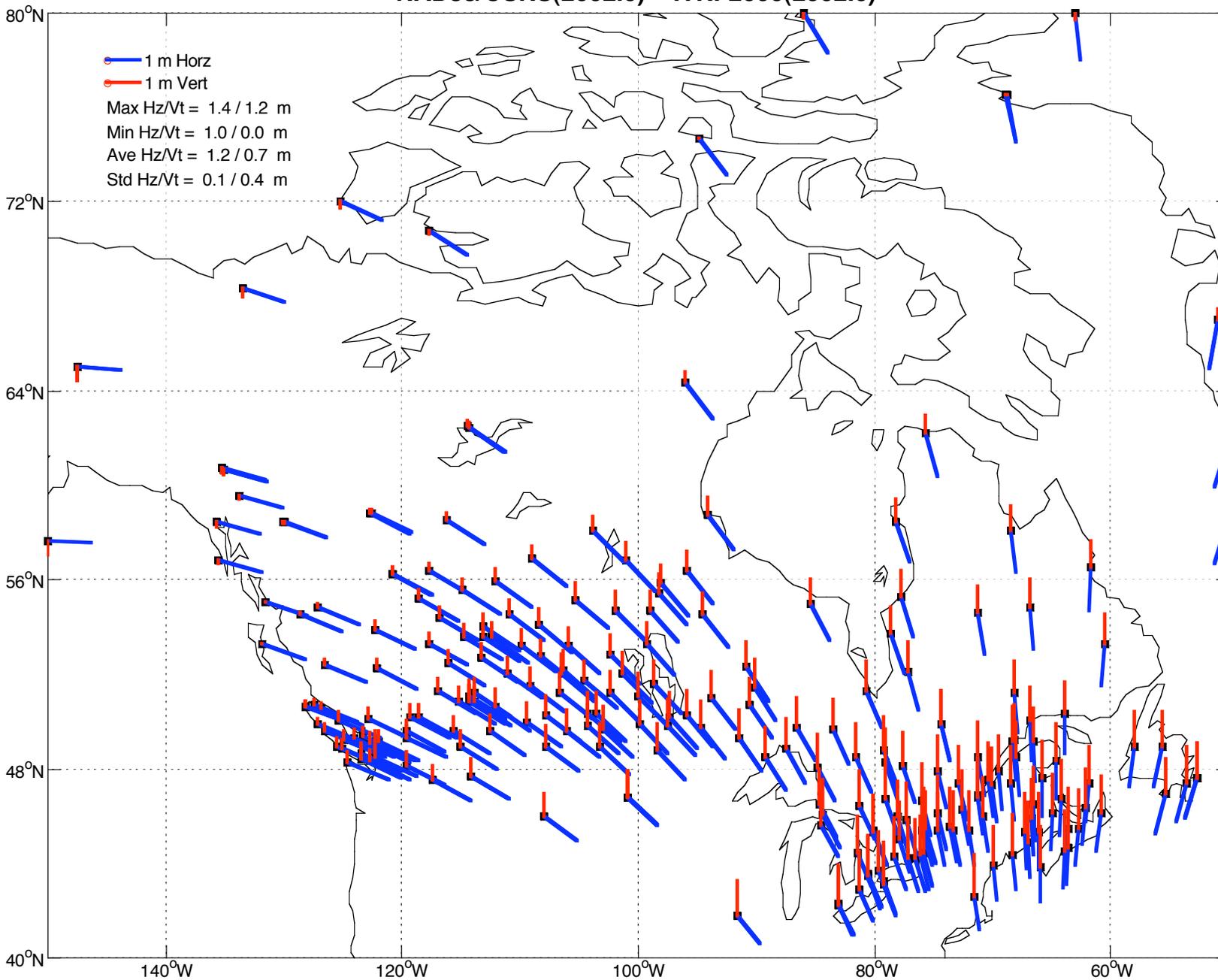


◆ GSD tracking sites   ◆ GSC tracking sites   ◆ Regional tracking sites

# North American Datum of 1983

- \* Origin is located about 2 meters from Earth's center.
- \* Orientation of axes differs from current international standard.
- \* Scale has been changed to agree with current international standard.

# NAD83/CSRS(2002.0) - ITRF2000(2002.0)



# Current definition of NAD 83

- The current realization of NAD 83 is called NAD 83 (CORS96) in the U.S. and NAD 83 (CSRS) in Canada.
- This realization is defined in terms of a 14-parameter Helmert transformation from ITRF00.
- This transformation is a composite of three separate transformation:

ITRF00 → ITRF97 → ITRF96 → NAD 83 (CORS96)

## *Reference Frame Transformation*

$$X_{\text{NAD}} = T_x + (1+S)X_{\text{ITRF}} + R_z X_{\text{ITRF}} - R_y X_{\text{ITRF}}$$

$$Y_{\text{NAD}} = T_y - R_z X_{\text{ITRF}} + (1 + S)Y_{\text{ITRF}} + R_x X_{\text{ITRF}}$$

$$Z_{\text{NAD}} = T_z + R_y X_{\text{ITRF}} - R_x Y_{\text{ITRF}} + (1 + S)Z_{\text{ITRF}}$$

# The ITRF96→NAD 83 (CORS96) transformation was defined so that:

- ITRF96 coordinates of 12 VLBI stations located in North America map onto their corresponding NAD 83 coordinates.
- Scale of NAD 83 = Scale of ITRF96 at epoch 1997.0.
- The mapping of horizontal velocities from ITRF96 to NAD 83 is consistent with the NUVEL1A-NNR model.
- The origin of NAD 83 does not drift relative to the origin of ITRF96.
- The scale of NAD 83 does not change in time relative to the scale of ITRF96.

# Transformation Parameters

## ITRF96 --> NAD\_83

Translations:  $T_x = 0.9910$  meters  
 $T_y = -1.9072$  meters  
 $T_z = -0.5129$  meters

Rotations:  $R_x = [25.79 + 0.0532X(t - 1997.0)]Xk$  radians  
 $R_y = [9.65 - 0.7423X(t - 1997.0)]Xk$  radians  
 $R_z = [11.66 - 0.0316X(t - 1997.0)]Xk$  radians

Scale change:  $S = 0.0$  (unitless)

# Transformation Parameters

## ITRF00 --> NAD\_83

Translations:  $T_x = 0.9956 + 0.0007 \cdot (t - 1997.0)$  meters  
 $T_y = -1.9013 - 0.0007 \cdot (t - 1997.0)$  meters  
 $T_z = -0.5215 + 0.0005 \cdot (t - 1997.0)$  meters

Rotations:  $R_x = [25.915 + 0.067X(t - 1997.0)]Xk$  radians  
 $R_y = [9.426 - 0.757X(t - 1997.0)]Xk$  radians  
 $R_z = [11.599 - 0.051X(t - 1997.0)]Xk$  radians

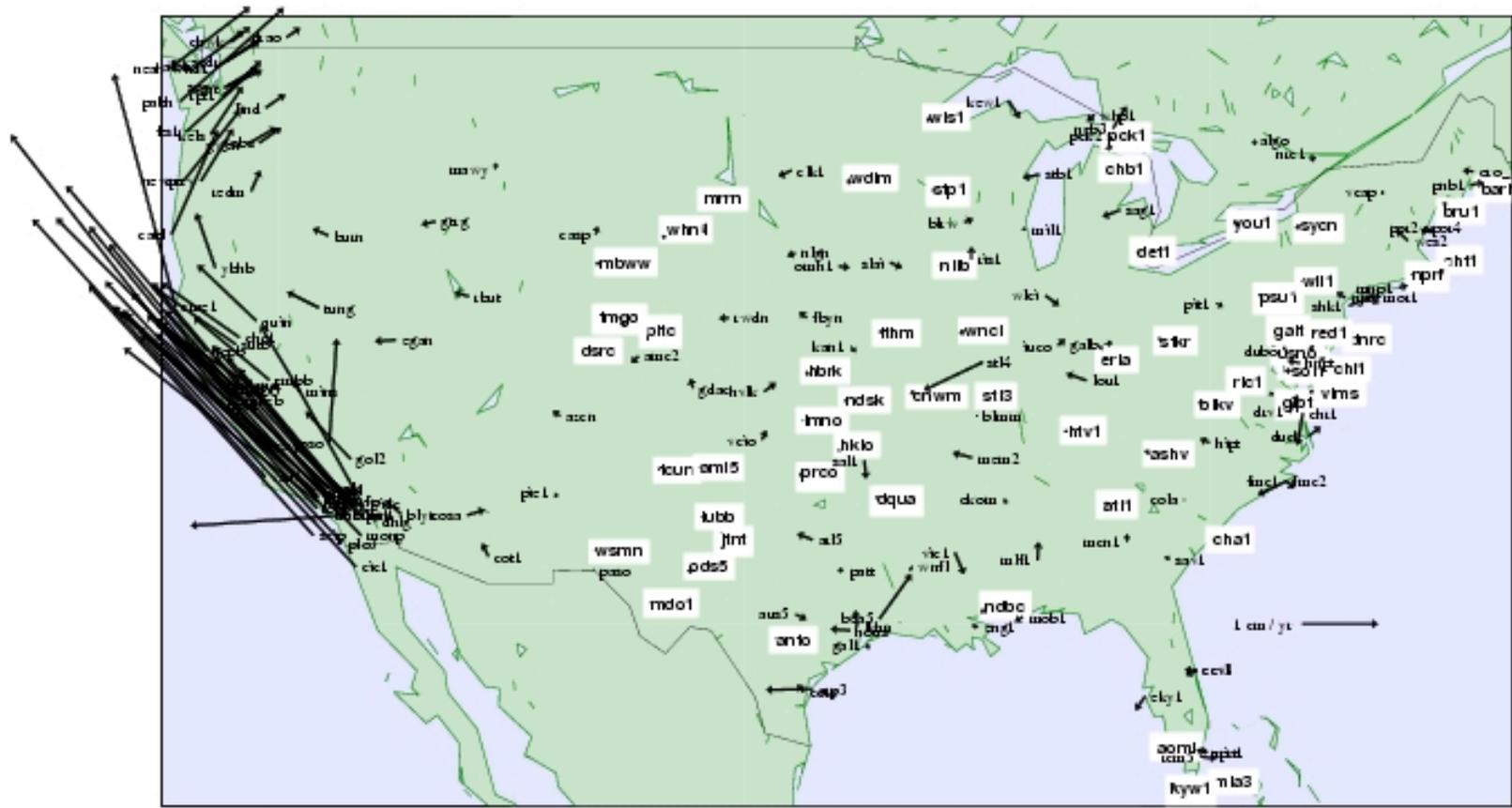
Scale change:  $S = 0.62 - 0.18 \cdot (t - 1997.0)$  ppb

# Transforming Positions

- Use HTDP (US) or TRNOBS (CA) software to transform positions between reference frames and from one epoch to another
- \* HTDP = Horizontal Time-Dependent Positioning  
Available at <http://www.ngs.noaa.gov>  
Click on “Geodetic Tool Kit”, then on “HTDP”
- \* TRNOBS = Transformation of Observations & Coords  
Available at <http://www.geod.nrcan.gc.ca>
- \* HTDP can also be used to predict horizontal velocities

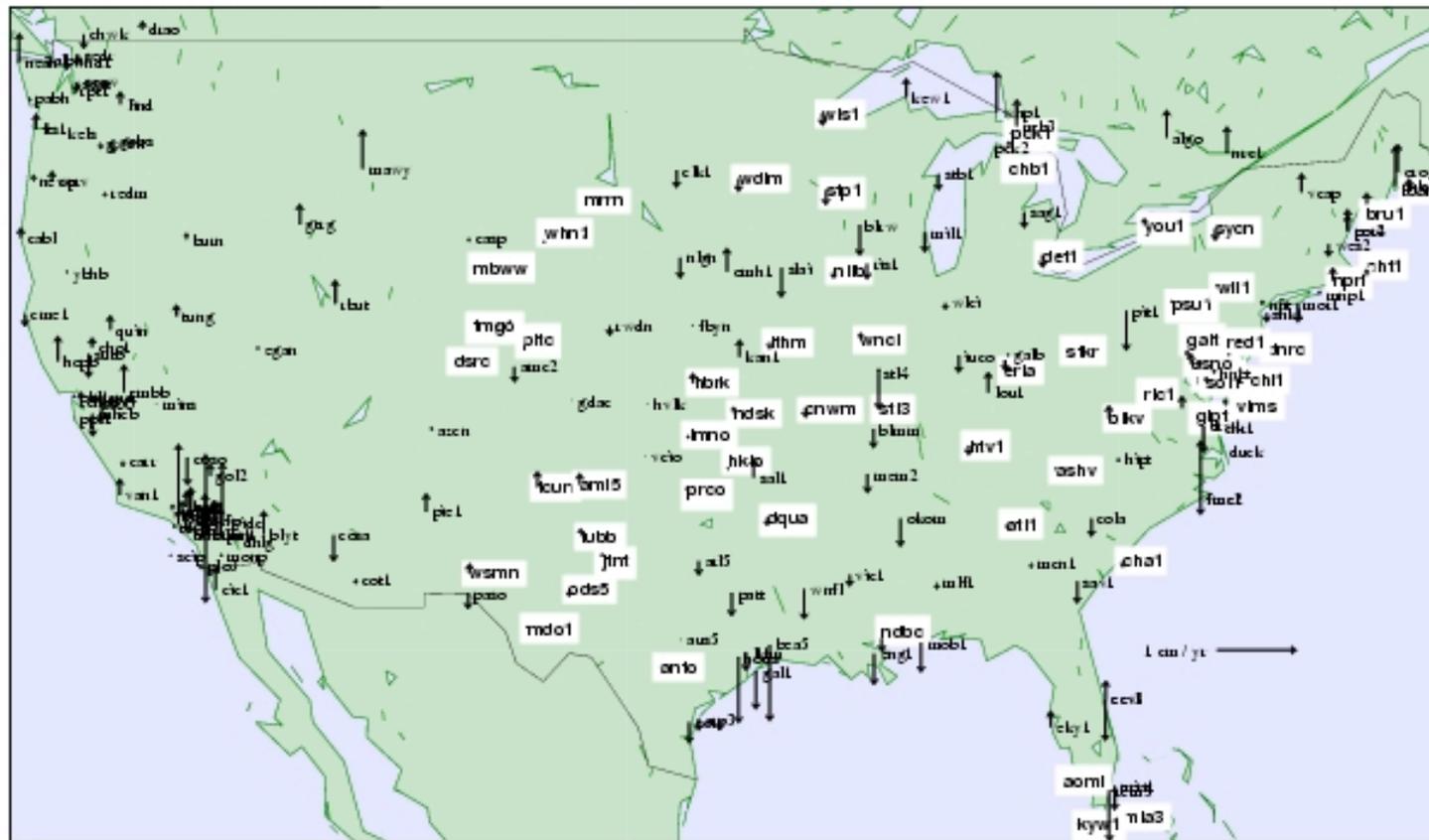


### CORS (Horizontal velocities relative to 'stable' sites)





### CORS (Vertical velocities relative to 'stable' sites)



# Towards a **Stable** Reference System for Expressing 3-D motion

- We defined this stable reference frame by constraining our solution to maximize the number of stations whose horizontal velocities are less than 1 mm/yr and whose vertical velocities are less than 2 mm/yr in magnitude.

# Towards a **Stable** Reference System for Expressing 3-D motion

- Our approach provides a mathematical-statistical basis for defining stability.
- The results of our approach depend upon the sample of reference stations. A sample of reference stations located exclusively in Canada or Mexico would likely yield a different concept for stable North America.

# How do we define a stable reference system for North America?

- Is there a geophysical basis for defining stability? (plate tectonics for horizontal motion; what if anything for vertical motion?)
- Are current plate motion models biased by the horizontal motion associated with glacial isostatic adjustment (a.k.a., postglacial rebound)?
- What about fluid withdrawal, seismic deformation, magmatic processes, sediment compaction, crustal loading/unloading, erosion, hydrological effects, seasonal effects, geocenter motion, etc.?